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#### Socio-environmental relations of nondiscrete spaces and architectures

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# Hierarchy in Flux

#### Scenario: Retrieve a airplane Blackbox

- \* Tele-operated robot with toolkit (controlled by umbilicus 6sec delay)
- Robot operators in control room (video, telemetry, sensor arrays)
- \* "Dry" testing environment



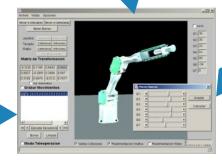
# Sociotechnical System



Leaders



Robot operators



Interface



Dry-testing



Tele-operated robot

#### Emergence: higher scale effects

Strong Emergence
"effects you could not anticipate or deduce"

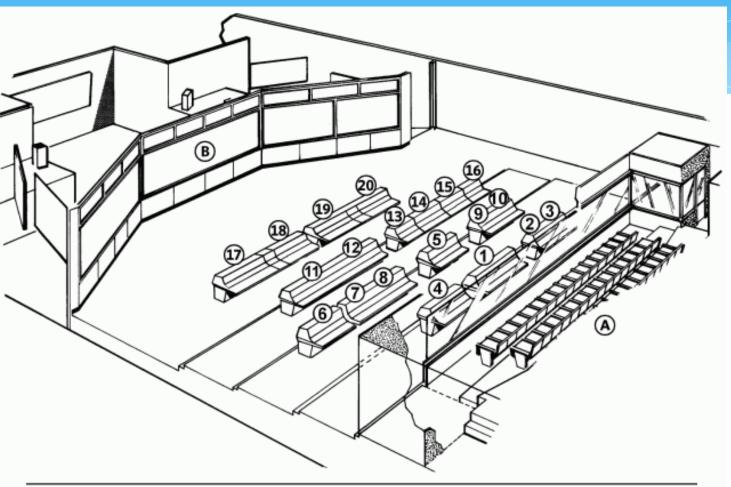
Weak Emergence
"predictable collective action"



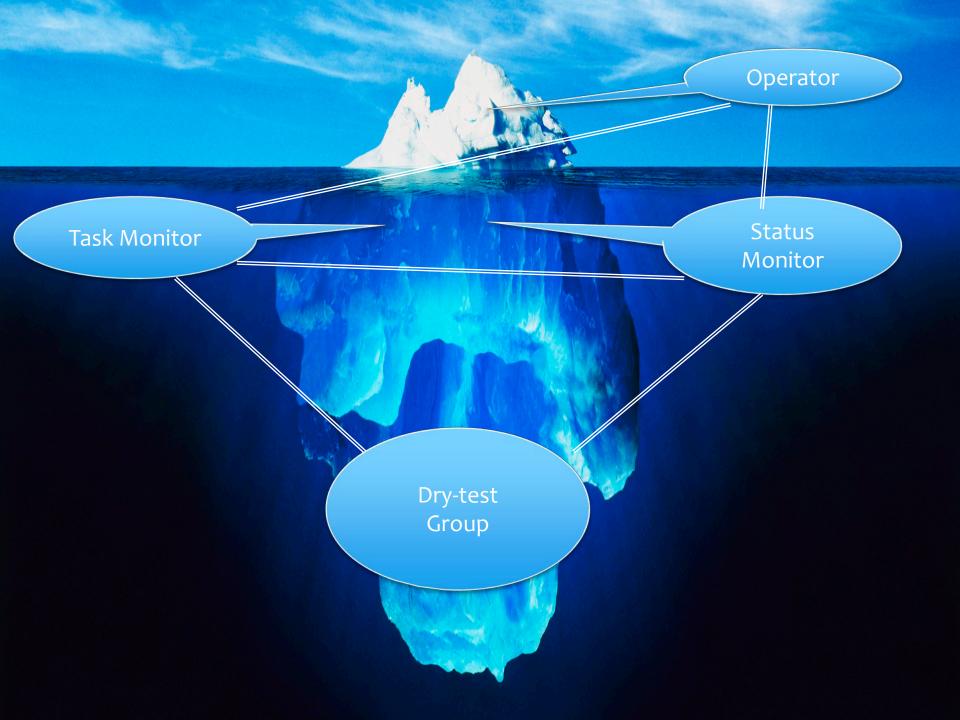
#### **Engineering Emergence**

- \* Maximize Weak Emergence
- \* Minimize (eliminate) strong emergence
- Limit interaction between parts of the system

### An Analogy



http://arstechnica.com/science/2012/10/going-boldly-what-it-was-like-to-be-an-apollo-flight-controller/



#### Why does this work?

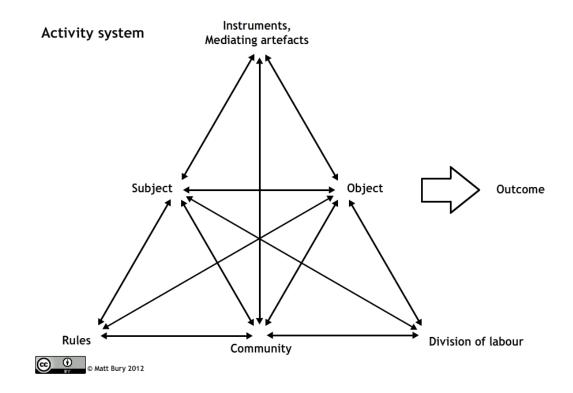
- Every role is specialized
  - Every specialist is focused on one small set of tasks
  - Every task is clearly defined
  - Inputs and outputs only go up or down one level
- \* It's a rigid and well-defined hierarchy that minimizes interaction and organizes the flow of communication and control
  - \* It is engineered not self-organizing

#### Wave Theory of HCI

- \* 1 Human Factors
  - Emphasizes human-machine coupling
  - Treats user as blackbox with inputs and outputs
- \* 2 Cognitivist
  - \* Emphasizes the work/task context
  - Supports the user as an intentional agent
- \* 3 Phenomenological
  - Emphasizes emergent uses of technology
  - Understands the user as a source of meanings

#### **Activity Theory**

- Decomposes activity into "Activity, Action, Operation" hierarchy.
- These closely map to Knowledge, Rules, and Skills, respectively.



#### Reconfiguring the Social Hierarchy

- \* How do we turn the rigid engineered system into a lightweight adaptable one?
  - Parsimony with variety
    - \* Co-locate personnel (from iceberg to ice cube)
    - Redundancy and variability of roles (flexibility of interface)
  - Automate skills (build them into the robot)
    - Dry-testing and modeling



# What does this have to do with interface design?

- \* Understanding context is important, but there is a problem with the unit of analysis (level of description)
  - \* We've designed a context but not an interface
  - \* More like a waterfall than co-evolution
- \* When we begin to look at the design of the interface itself a new set of dynamics begin to dominate
  - \* Perception, reasoning, situated-ness, communication

## How do we bridge the gap?

